TOSHIBA

De-palletizer



600pph high-speed handling of heavy items

- Items are pulled without centrifugal force, which enables quick unloading of heavy items.
- Depending on the stacking pattern, the robot automatically judges the number of items (either 1 or 2 items) which can be unloaded simultaneously for efficient unloading.



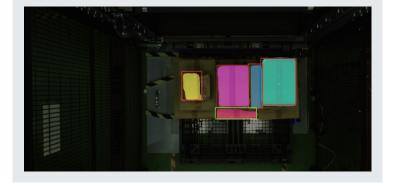
Careful handling of products

- Two-sided gripper (top and side) reduces stress to the product surface.
- The gripper pulls items instead of lifting, reducing risk of falling and/or breaking.



No prior programming required

- Image recognition technology enables the robot to handle various items in various stacking patterns.
- Short recognition time enables the robot to unload items smoothly.



Easy expansion

- The robot is space saving, requiring only 2.2 m x 3.4 m for installation.
- Can be used without a safety fence or surrounding buffer area.*



*Depending on system configuration or layout, a safety fence or other equipment may be required.

Specifications

ltem :	Description
Gripper type	Two-sided gripper (top and side)
Applicable containers	Flat pallets
Max. item size (mm)	$600\times600\times500$
Item weight (kg)	30 or less
Dimensions (mm)	$2200 \times 3400 \times 2700$ (excluding protruding part, control panel, and air compressors)
Throughput (pph)	600 (It may take different values depending on the size and stacking condition of items.)
Electricity supply	6k VA, three-phase 200 V (excluding compressors)
Environmental conditions	Ambient temperature: 0 to 40 °C, Relative humidity: 20 to 90%RH (Non condensing)

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https://www.toshiba.co.jp/sis/en/scd/logistics/index.htm Info available online

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